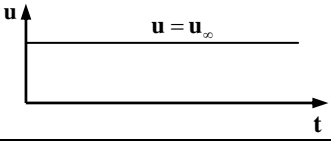
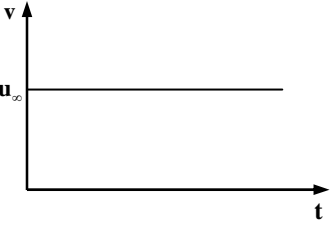
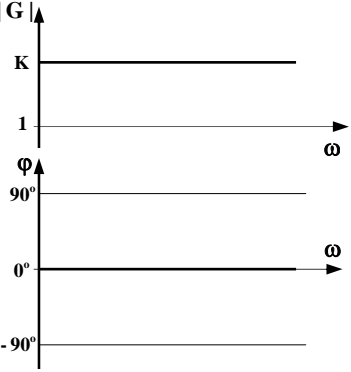
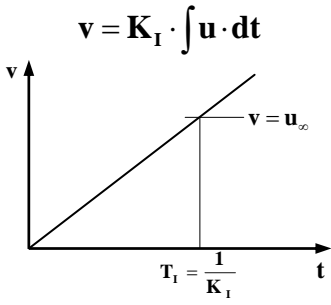
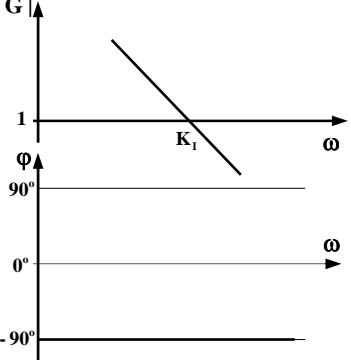
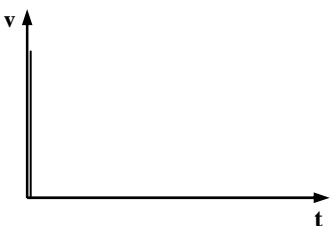
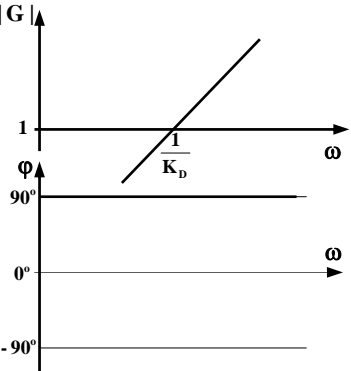
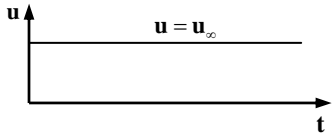
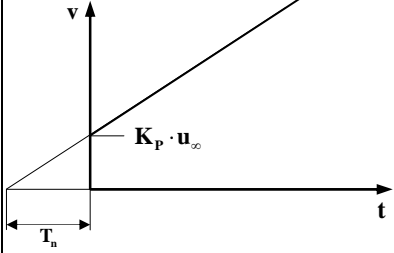
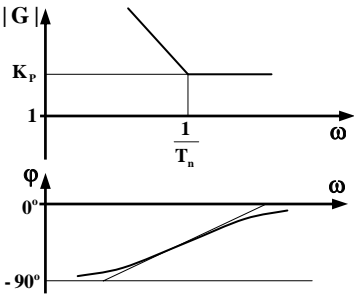
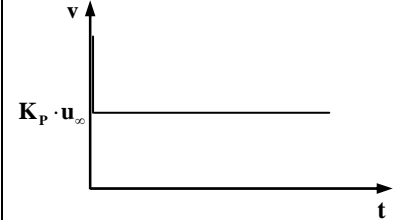
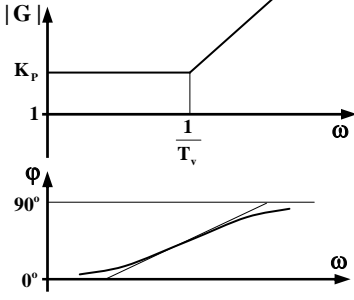
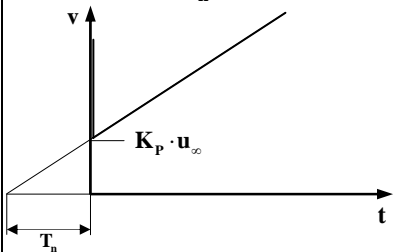
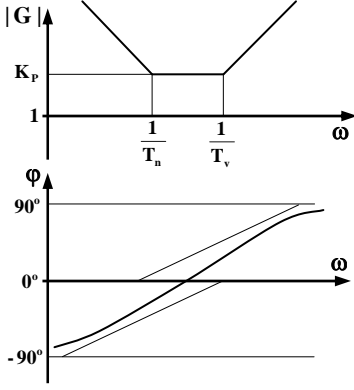
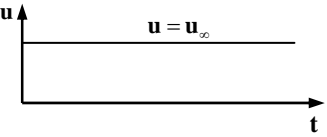
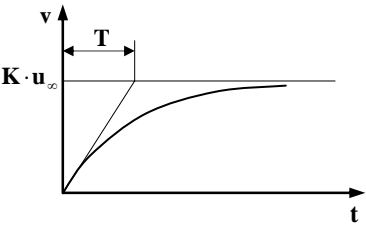
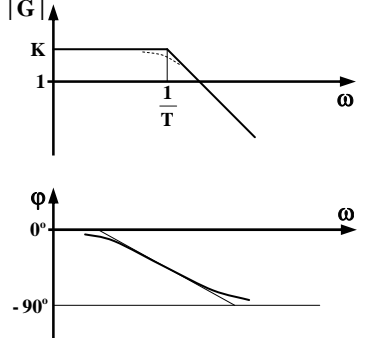
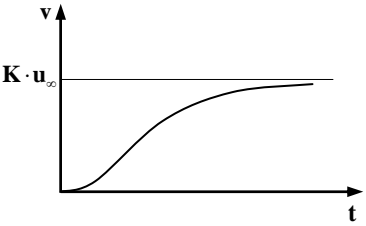
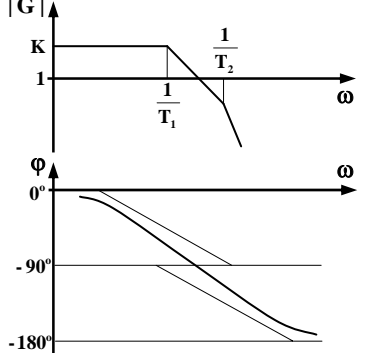
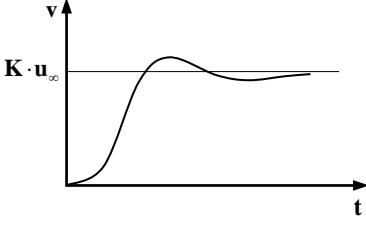
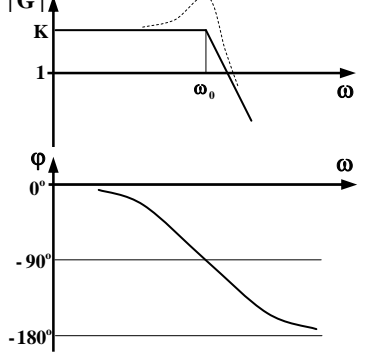
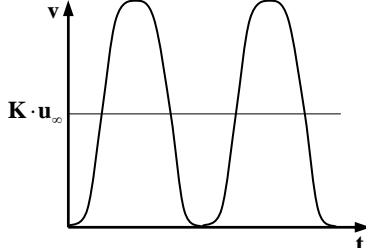
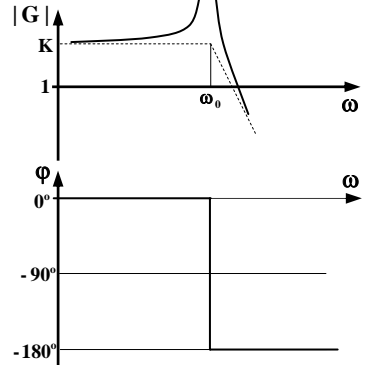
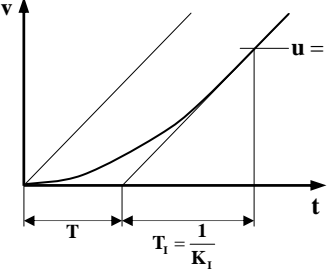
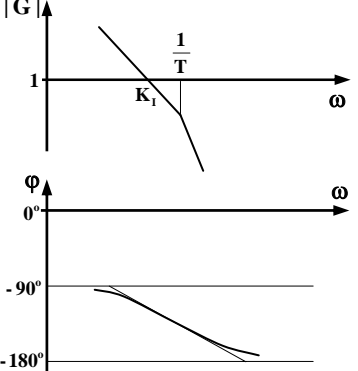
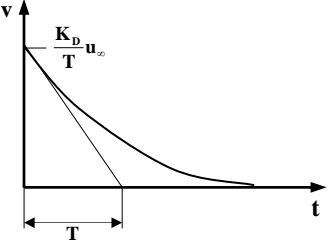
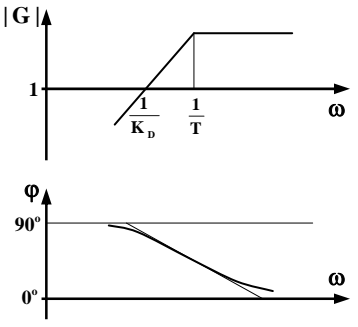
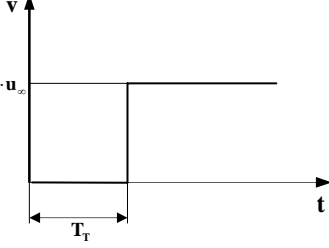


Bez.	Differentialgleichung und Sprungantwort	Frequenzgang	Bode-Diagramm Amplituden- und Phasengang
			
P	$v = K \cdot u$ 	$G = K$	
I	$v = K_I \cdot \int u \cdot dt$ 	$G = \frac{K_I}{j\omega}$	
D	$v = K_D \cdot \dot{u}$ 	$G = K_D j\omega$	

Bez.	Differentialgleichung und Sprungantwort	Frequenzgang	Bode-Diagramm Amplituden- und Phasengang
			
PI	$v = K_p \left(u + \frac{1}{T_n} \int u \cdot dt \right)$ 	$G = K_p \left(1 + \frac{1}{T_n j\omega} \right)$	
PD	$v = K_p (u + T_v \dot{u})$ 	$G = K_p (1 + T_v j\omega)$	
PID	$v = K_p \left(u + \frac{1}{T_n} \int u \cdot dt + T_v \dot{u} \right)$ 	$G = K_p \left(1 + \frac{1}{T_n j\omega} + T_v j\omega \right)$ <p>für $T_v \ll T_n$:</p> $G \approx K_p \left(1 + \frac{1}{T_n j\omega} \right) \cdot (1 + T_v j\omega)$	

Bez.	Differentialgleichung und Sprungantwort	Frequenzgang	Bode-Diagramm Amplituden- und Phasengang
			
PT ₁	$T \cdot \dot{v} + v = K \cdot u$ 	$G = \frac{K}{1 + j\omega T}$	
PT ₂	$T_1 T_2 \cdot \ddot{v} + (T_1 + T_2) \dot{v} + v = K \cdot u$ 	$G = \frac{K}{1 + (T_1 + T_2)j\omega + (T_1 T_2)(j\omega)^2}$	
PT ₂	$\ddot{v} + 2\delta\dot{v} + \omega_0^2 v = K\omega_0^2 u$ 	$G = \frac{K\omega_0^2}{\omega_0^2 + 2\delta j\omega + (j\omega)^2}$ <p style="text-align: center;">Dämpfungsgrad: $\frac{\delta}{\omega_0}$</p>	
PT ₂	$\ddot{v} + \omega_0^2 v = K\omega_0^2 u$ 	$G = \frac{K\omega_0^2}{\omega_0^2 + (j\omega)^2}$	

Bez.	Differentialgleichung und Sprungantwort	Frequenzgang	Bode-Diagramm Amplituden- und Phasengang
IT₁	$T \cdot \dot{v} + v = K_I \int u \cdot dt$ 	$G = \frac{K_I}{j\omega(1 + j\omega T)}$	
DT₁	$T \cdot \dot{v} + v = K_D \dot{u}$ 	$G = \frac{K_D j\omega}{1 + j\omega T}$	
PT_t	$v(t) = K \cdot u(t - T_T)$ 	$G = K \cdot e^{-j\omega T_T}$	